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(54) AUTOMATIC
HANDLING DEVICE OF
FREIGHT

(57) Abstract:

PURPOSE: To provide an automatic handling device of freight, which can command an optimum handling operation of freight to an industrial robot according to the opposing position against a pallet.

CONSTITUTION: A stacking up commanding device 7 is provided, in which the optimum handling operation of freight of an article 2 is computed for every pallet by the input function to input the relative positional relation of a pallet 6 and an industrial robot 3, and the command of handling operation of freight of the article 2 is output to the industrial robot 3 from the computed result. The same pattern can be individually processed for every pallet 6 following a different order of handling of freight by the optimum handling operation of freight of the article 2. Consequently, trouble of making of handling pattern of freight is reduced.

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